

Örnek: $L: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$

$L(A) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot A$, ile tanımlansın.

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

$$T = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\}$$

ve $\mathbb{R}^{2 \times 2}$ uzayının

iki sıralı bazıdır.

a) S b) T c) S ve T d) T ve S sıralı

bazılarına göre L 'nin temsilcilerini bulunuz.

$$a) \mathbb{R}_S^{2 \times 2} \rightarrow \mathbb{R}_S^{2 \times 2}$$

$$b) \mathbb{R}_T^{2 \times 2} \rightarrow \mathbb{R}_T^{2 \times 2}$$

$$c) \mathbb{R}_S^{2 \times 2} \rightarrow \mathbb{R}_T^{2 \times 2}$$

$$d) \mathbb{R}_T^{2 \times 2} \rightarrow \mathbb{R}_S^{2 \times 2}$$

$$a) \mathbb{R}_S^{2 \times 2} \rightarrow \mathbb{R}_S^{2 \times 2}$$

$$M = \left[\begin{array}{c} \left[\underline{L(s_1)} \right]_S \\ \left[\underline{L(s_2)} \right]_S \\ \vdots \\ \left[\underline{L(s_4)} \right]_S \end{array} \right]$$

$$L(s_1) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix}$$

$$L(s_2) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix}$$

$$L(s_3) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 4 & 0 \end{bmatrix}$$

$$L(s_4) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 4 \end{bmatrix}$$

$$\begin{aligned} & q_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + q_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + q_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \\ & + q_4 \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix} \\ & \downarrow \\ & q_1 = 1 \\ & q_3 = 3 \end{aligned}$$

$$M = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 2 \\ 3 & 0 & 4 & 0 \\ 0 & 3 & 0 & 4 \end{bmatrix} = [L]_{S,S}$$

$$b) [L]_{T,T} = M_2 \text{ (Alıştırmaya)}$$

$$M_2 = \begin{bmatrix} 4 & 3 & 0 & 3 \\ -6 & -5 & -6 & -2 \\ 3 & 3 & 7 & 0 \\ 8 & 7 & 6 & 3 \end{bmatrix}$$

$$c) \quad L: R_s^{2 \times 2} \rightarrow R_T^{2 \times 2}$$

$$M_3 = \begin{bmatrix} [L(s_1)]_T & [L(s_2)]_T & [L(s_3)]_T & [L(s_4)]_T \end{bmatrix}$$

$$L(s_1) = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix} = a_1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + a_2 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + a_3 \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} + a_4 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$L(s_2) = \begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} =$$

$$L(s_3) = \begin{bmatrix} 2 & 0 \\ 4 & 0 \end{bmatrix} =$$

$$L(s_4) = \begin{bmatrix} 0 & 2 \\ 0 & 4 \end{bmatrix} =$$

$$a_1 + a_2 + a_3 = 1 \quad 0 \quad 2 \quad 0$$

$$a_2 + a_4 = 0 \quad 1 \quad 0 \quad 2$$

$$a_3 = 3 \quad 0 \quad 4 \quad 0$$

$$a_4 = 0 \quad 3 \quad 0 \quad 4$$

$$\left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 & 2 & 0 \end{array} \right] \xrightarrow{-s_1 + s_4} \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 1 & 1 & 0 & 1 & -3 & 2 & -4 \end{array} \right] \sim$$

$$\begin{aligned} q_1 + q_2 + q_3 &= 1 & 0 & 2 & 0 \\ q_2 + q_4 &= 0 & 1 & 0 & 2 \\ q_3 &= 3 & 0 & 4 & 0 \\ q_1 &= 0 & 3 & 0 & 4 \end{aligned}$$

$$\xrightarrow{-s_2 + s_4} \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 1 & -1 & 1 & -4 & 2 & -6 \end{array} \right] \xrightarrow{-s_3 + s_4} \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & -1 & -2 & -4 & -2 & -6 \end{array} \right]$$

$$-s_4 \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & 1 & 2 & 4 & 2 & 6 \end{array} \right]$$

$$-s_4 + s_1 \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 0 & -2 & -3 & -2 & -4 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & 1 & 2 & 4 & 2 & 6 \end{array} \right]$$

$$\downarrow$$

$$\left[L(s_1) \right]_T$$

$$\left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 1 & 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 & 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & -1 & -2 & -4 & -2 & -6 \end{array} \right]$$

$$M_3 = \left[\begin{array}{cccc} 0 & 3 & 0 & 4 \\ -2 & -3 & -2 & -4 \\ 3 & 0 & 4 & 0 \\ 2 & 4 & 2 & 6 \end{array} \right] : L_{s,T}$$

$$d) L: R_T^{2 \times 2} \rightarrow R_S^{2 \times 2} : [L]_{T,S} = M_4 = ?$$

(Alıştırma.)

Örnek: $L: P_1 \rightarrow P_2$, $L(p(t)) = t \cdot p(t) + p(0)$

şeklinde tanımlanıyor.

$$S = \{t, 1\} \text{ ve } S' = \{t+1, t-1\} \quad P_1 \text{ in,}$$

$$T = \{t^2, t, 1\} \text{ ve } T' = \{t^2+1, t-1, t+1\} \quad P_2 \text{ nin}$$

sıralı bazları ise; L nin

a) S ve T sıralı bazlarına göre,

b) S' ve T' " "

temsilcilerini
bulunuz.

(b) $L: P_1 \rightarrow P_2$
 $(s') \quad (t')$

$$M = \left[\left[L(s'_i) \right]_{T'}, \left[\left[L(s'_i) \right]_{T'} \right] \right] =$$

$$L(t+1) = t \cdot (t+1) + 1 = t^2 + t + 1 = a_1(t^2+1) + a_2(t-1) + a_3(t+1)$$

$$L(t-1) = t \cdot (t-1) - 1 = t^2 - t - 1 = \text{---} \text{---} \text{---} \text{---} \text{---} \text{---}$$

$$a_1 t^2 + (a_2 + a_3)t + (a_1 - a_2 + a_3) = (t^2 + t + 1)' = (t^2 - t - 1)$$

$$\begin{aligned} a_1 &= 1 \\ a_2 + a_3 &= 1 \\ a_1 - a_2 + a_3 &= 1 \end{aligned} \left\{ \begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & -1 \\ 1 & -1 & 1 & 1 & -1 \end{array} \right\} \xrightarrow{-S_1 + S_3} \sim \left\{ \begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & -1 \\ 0 & -1 & 1 & 0 & -2 \end{array} \right\}$$

$$S_2 + S_3 \sim \left[\begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & -1 \\ 0 & 0 & 2 & 1 & -3 \end{array} \right] \xrightarrow{\frac{1}{2}S_3} \left[\begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & -1 \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{3}{2} \end{array} \right]$$

$$-S_3 + S_2 \sim \left[\begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{3}{2} \end{array} \right]$$

$$\left[\begin{array}{ccc|c|c} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & -1 \\ 0 & -1 & 1 & 0 & -2 \end{array} \right]$$

$$M = \left[\begin{array}{cc} 1 & 1 \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{3}{2} \end{array} \right] \checkmark$$

Ⓐ Sıkı
Ağırtıma.

Benzerlik:

Teorem: $L: V \rightarrow W$ bir lineer dönüşüm,

$\text{boy}(V)=n$ ve $\text{boy}(W)=m$ olsun.

V nin iki sıralı bazı S ve S' ; W nun iki sıralı bazı T ve T' olsun. Eğer L nin

V ve W nun S ve T bazlarına göre temsilcisi A matrisi ise; $P = P_{S \leftarrow S'}$ ve

$Q = Q_{T \leftarrow T'}$ geçiş matrisleri olmak üzere

L nin S' ve T' bazlarına göre temsilcisi $B = Q^{-1} A P$ matrisi olur.

$$L: V_S \rightarrow W_T, \quad [L]_{S,T} = A$$

$$L: V_{S'} \rightarrow W_{T'}, \quad [L]_{S',T'} = B = Q^{-1} A P$$

Input: Her $x \in V$ is in $\frac{[L(x)]_T = A \cdot [x]_S}{[L(x)]_{T'} = Q^{-1} [L(x)]_T}$

$$P \cdot [x]_{S'} = [x]_S$$

$$[x]_{S'} = \bar{P}' [x]_S$$

$$(Q^{-1} = Q_{T' \leftarrow T})$$

$$[L(x)]_{T'} = Q^{-1} [L(x)]_T = \underbrace{(\bar{Q}' A P)}_{B \cdot [x]_{S'} = [L(x)]_{T'}} [x]_{S'}$$

□

$$L: V \rightarrow W$$

$\frac{S}{S_1}$	$\frac{T}{T_1}$
S_2	T_2
\vdots	\vdots

$$[L]_{S,T} \stackrel{?}{\sim} [L]_{S',T'}$$

\parallel \parallel
 A B

$$B = Q^{-1} \cdot A \cdot P$$

$$Q: T \leftarrow T'$$

$$P: S \leftarrow S'$$

Örnek: $L: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $L\left(\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}\right) = \begin{bmatrix} a_1 + a_3 \\ a_2 - a_3 \end{bmatrix}$

lin. döns. veriliyor.

\mathbb{R}^3 ün iki sıralı bazı $S = \text{Standard Baz}$,

$S' = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ ve \mathbb{R}^2 nin iki

sıralı bazı $T = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ ve $T' = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}$

olsun.

a) L nin S ve T sıralı bazlarına göre temsilcisi?

b) $P_{S \leftarrow S'}$ ve $Q_{T \leftarrow T'}$ geçiş matrisleri?

c) L nin S' ve T' bazlarına göre temsilcisi?

(a) ve (b) den yararlanarak bulunur.

d) L nin S' ve T' bazlarına göre temsilcisi?

döğrudan bulunur.

$$(a) [L]_{S,T} = A = \begin{bmatrix} [L(s_1)]_T & [L(s_2)]_T & L(s_3) \end{bmatrix}$$

$$L \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} a_1 + a_3 \\ a_2 - a_3 \end{bmatrix}$$

$$\left. \begin{array}{l} L \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow [L(s_1)]_T = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ L \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow [L(s_2)]_T = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ L \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rightarrow [L(s_3)]_T = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \end{array} \right\} A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \end{bmatrix}$$

$$\textcircled{b} \quad P_{S \leftarrow S'} = \begin{bmatrix} [s_1']_S & \vdots & [s_2']_S & \vdots & [s_3']_S \end{bmatrix}$$

$$a_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + a_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \vdots \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \vdots \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right]$$

$$P_{S \leftarrow S'}$$

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$Q_{T \leftarrow T'} = Q \Leftrightarrow Q^{-1} = Q_{T' \leftarrow T}$$

$$\begin{bmatrix} [t_1]_{T'} & \vdots & [t_2]_{T'} \end{bmatrix} = Q^{-1} \Rightarrow a_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 1 & 3 & 0 & 1 \end{array} \right]$$

$$-S_1 + S_2 \quad \left[\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 2 & -1 & -1 & 1 \end{array} \right] \xrightarrow{\frac{1}{2} S_2} \left[\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & -1/2 & -1/2 & 1/2 \end{array} \right]$$

$$-S_2 + S_1 \quad \left[\begin{array}{cccc|c} 1 & 0 & 3/2 & -1/2 & -1/2 \\ 0 & 1 & -1/2 & -1/2 & 1/2 \end{array} \right] \Rightarrow Q^{-1} = \begin{bmatrix} 3/2 & -1/2 \\ -1/2 & 1/2 \end{bmatrix}$$

$\underbrace{\quad\quad\quad}_{I_2} \quad \underbrace{\quad\quad\quad}_{Q^{-1}}$

$$\left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 1 & 3 & 0 & 1 \end{array} \right]$$

$\underbrace{\quad\quad}_{-I_2}$

$$\textcircled{c} [L]_{S', T'} = \beta = Q^{-1} A P, \quad A = [L]_{S, T}$$

$$B = \underbrace{\begin{bmatrix} 3/2 & -1/2 \\ -1/2 & 1/2 \end{bmatrix}}_{Q^{-1}} \cdot \underbrace{\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \end{bmatrix}}_A \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_P$$

$$B = \frac{1}{2} \begin{bmatrix} 3 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 & 3 & 4 \\ 0 & -1 & -2 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 3/2 & 2 \\ 0 & -1/2 & -1 \end{bmatrix} \neq$$

$$B = Q^{-1} A P$$

(d) $B = \left[\left[L(s'_1) \right]_{\tau'} \left[L(s'_2) \right]_{\tau'} \left[L(s'_3) \right]_{\tau'} \right] = \left[\left[\begin{pmatrix} 1 \\ 1 \end{pmatrix} \right]_{\tau'} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix} \right]_{\tau'} \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} \right]_{\tau'} \right]$

s', τ'

$$a_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\left[\begin{array}{cc|cc|cc|c} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 3 & 1 & 1 & 0 & 1 & -1 \end{array} \right] \xrightarrow{-S_1 + S_2} \left[\begin{array}{cc|cc|cc|c} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 2 & 0 & 0 & -1 & 0 & -2 \end{array} \right]$$

$$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}_T, \begin{bmatrix} 1 \\ 0 \end{bmatrix}_T, \begin{bmatrix} 1 \\ -1 \end{bmatrix}_T \right\}$$

$$\frac{1}{2} S_2 \left[\begin{array}{cc|cc|cc|c} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & -1/2 & 0 & 1 & -1 \end{array} \right] \xrightarrow{-S_2 + S_1} \left[\begin{array}{cc|cc|cc|c} 1 & 0 & 1 & 3/2 & 2 & 0 & 1 \\ 0 & 1 & 0 & -1/2 & -1 & 0 & 1 \end{array} \right]$$

$\underbrace{\hspace{10em}}_{I_2} \quad \underbrace{\hspace{10em}}_B$

$$[L]_{S', T'} = B = \begin{bmatrix} 1 & 3/2 & 2 \\ 0 & -1/2 & -1 \end{bmatrix}$$

Sonuç: $L: V \rightarrow V$, n boyutlu V uzayı
 üzerinde bir lineer operatör (dönüşüm) olsun.
 S ve S' ; V nin iki sıralı bazı ve
 $P_{S \leftarrow S'} = ?$ olmak üzere; L nin S
 bazına göre temsilcisi A ile S' bazına göre
 temsilcisi B arasındaki ilişki;

$$B = P^{-1} \cdot A \cdot P \text{ d.i.}$$

$$\left. \begin{array}{l} L: v \rightarrow w \\ \begin{array}{cc} s & t \\ s' & t' \end{array} \end{array} \right\} \begin{array}{l} L: V \rightarrow V \\ \begin{array}{cc} s & s \rightarrow A \\ s' & s' \rightarrow B \end{array} \end{array}$$